Amendments to the Specification:

Please replace paragraph **[0060]** with the following rewritten paragraph:

[0001] Fig. 11 shows another uncertainty field using a determination of an instantiation of sensing field based on the Cramer-Rao bound (CRB) of estimation accuracy, or, equivalently, the Fisher information, in sensor networks. Fig. 11 involves the determinant of the distributed Fisher information. Details of the determination may be found in Liu, Juan, et al., "Sensing Field: Coverage Characterization in Distributed Sensor Networks", Proceedings of ICASSP, May 2003, the entirety of which is hereby incorporated by reference. Fig. 11 is plotted in log scale.